



Linear MOTIONEERING[®] User's Guide

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Linear MOTIONEERING[®]

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1 General Information

1.1 About this User's Guide

This document provides a step-by-step procedure for using the Linear MOTIONEERING[®] software tool. Each screen of the tool is explained and user response options are clarified.

• A

This symbol is used throughout this guide to alert the user to helpful information.

•

This symbol is used throughout this guide to warn the user of critical information.

1.2 General navigational instructions for using this web tool

1	2	3	4	5	6	7	8	9
Ноте	My Application					My Account	Help	Tech Support

- The navigation bar at the top of your screen can be used to access the 1) Linear MOTIONEERING[®] Home Page, 2) your application in progress, 3) all the solutions that meet your application requirements, 4) your selected system from the solution set, 7) your account setup and preference configuration, 8) Linear MOTIONEERING[®] program help, and 9) technical support contact information. Clicking on the various dark gray headers will take you to the desired screen. When headers are light gray, they are unavailable.
- To move to the next screen, click the CONTINUE button. To move back to a previously viewed screen, click the Back button of your web browser or the BACK button in the upper right of the screen (if available).
- If clicking the CONTINUE button does not move you to another screen, check the current screen for an error message. You might have to scroll down to see the message. The error message will prompt you for more information or to correct information entered.
- To use a drop-down list box, click the arrow to the right of the selection box. This will display a list of available options. Select the desired option from the list by clicking on it.
- To select an option from a bulleted list, click on the circle next to the desired option.
- To enter a value in a value box, click on the box to place your cursor inside, then type your desired value. Do not enter units such as "lbf" or "mm" in a value box. These can be selected from drop-down list boxes to the right of the value boxes when applicable.
- When viewing a table list there may be some list items out of view. To view these items, click the arrows on the vertical or horizontal scroll bar or click and drag the bar to the desired location.
- If an option is grayed out it is either unavailable or inapplicable for your chosen system, or it is the only option and may not be modified.

1.3 Saving and Managing Application Data – My Account Screen

Application data may be saved any time after the completion of Step 1. To do so, click SAVE CURRENT DATA located at the bottom of the side menu to the left of each step.

1.3.1 Log-in Screen

 New accounts: To create an Linear MOTIONEERING[®] account, click the CONTINUE button in the box headed 'No, I need to create a User ID and Password'.





Enter user information in the appropriate fields. Information in the yellow fields is required. When finished, click SUBMIT. Clicking CLEAR FIELDS will delete all user information from the page. Clicking CANCEL will clear all information and return the user to the log-in screen. To return to the previous screen, use the web browser's Back button, BACK at the upper right of the current screen, or the MY APPLICATION tab.

Linear MOTIONEERING[®] uses the email address as a UserID and will not allow the creation of duplicate accounts with the same email address. To request a password reminder refer to the instructions below.

- Existing accounts: Enter UserID (user's complete email address) and password, then click CONTINUE.
 - Passwords are case sensitive. For a password reminder click FORGOT YOUR PASSWORD? and follow the prompts. Linear MOTIONEERING[®] will send the correct password to the email address specified. Click RETURN TO LOGIN PAGE to log in.

User ID (Email Address)	
Password [case sensitive]	
	Continue

1.3.2 My Account

This screen allows users to change account information, start a new application, and save and retrieve application data.

y Account				4
Welcome	. Your last successfi	ul login was on		Log Ou
Update your Account Information	n			
Change your User Profile	Change your address, company infor	mation, email address etc.		
Change your Password	Change your password from the syst	tem generated password. A good security measure	2	
Start a New Application				
Start a New Application	This will begin a new application. Cli	iolong any of the Bave Data links will return you to th	is page to save your data.	
Bave your Application Data		Your Current Solution Files are a	chown below	
Save to a New File		Save to an Existing File		
Enter File Name	Save	sample3	Detete	Overorite
		sample4	Delete	Overwrite
		sample5 finished app	Delete	Overwrite
		sample5 finished app	Delete	<u>Overwrite</u>
Retrieve your Application Data				
		sample3	Batrie	<u>49</u>
		sample4	Betrie	MB
		sample5 tinished app	Batrie	<u>M8</u>
		sample& finished app	Batrie	48

If a session is inactive for 45 minutes Linear MOTIONEERING[®] will generate an error message. All unsaved data will be lost. Click BEGIN NEW SOLUTION to return to the Linear MOTIONEERING[®] Home Page.

1.3.2.1 Update your Account Information

• Clicking CHANGE YOUR USER PROFILE will open a screen headed 'Update Profile'. Information in yellow fields is required.

the fields you you First Name:	Dana	he	gairea neias are marke	d with Yellor
Last Name:	Jones			
Title:				
Company:	Manufacturing Company, Inc.			
hone Number:	556-556-5665	100		
Fax Number:				
Email:	djones@company.com	Note: Changing your	email changes you	r login Use
treet Address:	1			
itreet Address: Idg, Apt, Suite,]
dg, Apt, Suite,		State:	Virginia	
dg, Apt, Suite, Mail Stop: City: Zip Code or	55655		Virginia United States	-
dg, Apt, Suite, Mail Stop: City:	55655	State:	The second s	-
dg, Apt, Suite, Mail Stop: City: Zip Code or		State:	The second s	-
dg, Apt, Suite, Mail Stop: City: Zip Code or	55655 Submit Cancel	State:	The second s	-

Linear MOTIONEERING[®] uses the email address as a UserID for the account. Changing the address results in changing the UserID. Account password remains the same.

Click SUBMIT to save changes and return to the 'My Account' page. Click CANCEL to cancel changes and return to the 'My Account' page.

 Click CHANGE YOUR PASSWORD to create a new password. Passwords are case sensitive. Click SUBMIT to save the revised password. To exit without saving the revised password return to the 'My Account' screen by clicking either the Back button on your web browser or BACK at the upper right of the Linear MOTIONEERING[®] screen.

Confirm	New Pa	ssword	1
_		4	

1.3.2.2 Start a New Application

Start a New Application

Start a New Application

This will begin a new application. Clicking any of the Save Data links will return you to this page to save your data.

 Clicking START A NEW APPLICATION opens the Linear MOTIONEERING[®] Home Page. (Refer to <u>section</u> <u>2</u> of this user guide for instructions on beginning a new selection process). Applications may be saved after completing Step 1 of the process by clicking SAVE CURRENT DATA or by clicking the MY ACCOUNT tab. This will return you to the 'My Account' screen. Refer to <u>section 1.3.2</u> of this user guide for details.

1.3.2.3 Save Your Application Data

This section of the 'My Account' screen allows the user either to save an application to a new file or save it as an update to an existing file. Files may also be deleted.

we your Application Data	Your Current Solution Files are s Save to an Existing File	hown below	
nter File Name	sample3	Delete	<u>Overwrite</u>
	sample4	Delete	Overwrite
	sample5 finished app	Delete	Overwrite
	sample6 finished app	Delete	Overwrite

- To save an application to a new file, enter a file name in the value box and click SAVE. The saved application will appear in the list box to the right and a confirmation message will appear below.
- To save an application to an existing file, click OVERWRITE in the row next to the file name. A confirmation message will appear below.

Do NOT enter a File Name in the value box if you wish to overwrite an existing file.

• To delete an existing application file, click DELETE in the row next to the file name.



Linear MOTIONEERING[®] will NOT prompt for confirmation before deleting the file. After deleting the file a confirmation message will appear below.

1.3.2.4 Retrieve Your Application Data

Retrieve your Application Data

sample3	Retrieve	
sample4	Retrieve	
sample5 finished app	Retrieve	
sample6 finished app	Retrieve	

• To retrieve an existing application file, click RETRIEVE in the row next to the file name. Linear MOTIONEERING[®] will return you either to Step 6 of your application or to the most recently completed screen prior to Step 6.

1.3.2.5 Finish

• To log out and return to the last Linear MOTIONEERING[®] application design screen, click FINISH.

2 Begin Using Linear MOTIONEERING®

This screen is the starting point for two different selection processes: 1) *Sizing and Selection,* or 2) *Configuration and Quoting.*



2.1 Sizing and Selection

The Sizing and Selection option allows the user to enter application sizing information. Linear MOTIONEERING[®] filters product choices based on application data entries. Users may choose from a list of applicable products, create and download 2D and 3D CAD drawings, access catalog data, request a quote, save the application for future reference or modification, or print the specifications. To choose this option, click CONTINUE. Refer to <u>section 3</u> of this user guide for step by step instructions.

2.2 Configuration and Quoting

The Configuration and Quoting option is a shortcut for those already familiar with Thomson products. Models can be searched by product family or by part number. This option allows the user to download custom 2D and 3D CAD models in a variety of formats and request a quote. To search from a list of products, select the product family from the drop-down list box, then click CONTINUE. To search by part number, click LOOKUP BY PART NUMBER, then click CONTINUE. Refer to section 4 of this user guide for continued instructions.

2.3 Linear MOTIONEERING[®] Site Flowchart



3 Sizing and Selection

3.1 Mechanical System Design

3.1.1 System Orientation (Step 1 Screen 1)

Click on one of the four images that best fits the orientation of your application.



Application data can be saved as early as completion of this initial Step 1.



Orientation Selected None

3.1.2 Mounting Configurations (Step 1 Screen 2)

This screen describes up to three possible mounting configurations depending on system orientation:

- Fully Supported: A linear system whose base is continuously supported for its entire slide length. Selecting this option does not filter out any systems.
- End Supported: A linear system supported by only two supports located towards the ends of the slide. This system is designed to span a gap and be self supporting in the application. Clear span distance and end support widths will be required for entry in the steps following.
 - Only Movopart (TG/TF) and Rapidtrak (MG/MF) units are available in this support type. Selecting this option will remove all other systems from consideration.



• Intermittently Supported: A system usually requiring relatively long lengths where full or end support is impractical. The greatest span distance between any two adjacent supports will be required for entry in the steps following.



Only Movopart (TG/TF), Rapidtrak (MG/MF), and SuperSlide (RB/RE) units are available in this support type. Selecting this option will remove all other systems from consideration.

Select by clicking on the image that best fits your application or click CHANGE ORIENTATION to return to System Orientation.



Application data can be saved as early as completion of this initial Step 1.

Positioning Requirements (Step 2) 3.1.3

This screen collects information regarding stroke length, accuracy, repeatability, backlash and travel life.

Accuracy	No Preference	v ()
	NO FIEIEIEICE	
🖹 Repeatability	No Preference	× 0
Maximum Allowable Backlash	No Preference	× 0
Travel Life	10,000,000 in 🕑 Use default	\leq
Contraction of the second seco	Accuracy, repeatability and backlash	
	ined from hard stop to hard stop If utilizing limit switches, adjust a decelerate before reaching end of stroke	troke to sllow your
	Please click Continue, when complete	Continue

3.1.3.1 Stroke Length

Enter a stroke length and select the unit of measure from the unit selection box. Stroke length is not adjusted for the addition of limit switches or over travel conditions (refer to Appendix A for more details). Adjust stroke length to allow your motor/control package to decelerate before reaching the end of the stroke.

3.1.3.2 Accuracy, Repeatability, Backlash

Decide which of these values is most critical in your application. Select a value range from the selection box. Selecting a range in one box will alter the values in the other two boxes.

- Absolute Accuracy is defined as the maximum error between expected and actual position. Factors include accuracy of the motor/drive system, lead screw pitch error (lead accuracy), and system backlash (drive train, lead screw and nut assembly). See Appendix A for more details.
- Repeatability is defined as the ability of a positioning system to return to a location during operation when approaching from the same direction, at the same speed and deceleration rate. Factors include angular repeatability of the motor/drive system, system friction, and changes in load, speed, and deceleration. See Appendix A for more details.
- Backlash is defined as the amount of play (lost motion) between a set of moveable parts. Factors include lead screw wear (acme), drive train wear, and spaces between moving parts. See Appendix A for more details.





Note: Stroke length is defined from hard stop to hard stop.lf utilizing limit switches, adjust stroke to allow your motor/control package to decelerate before reaching end of stroke

Life Calculator

If you need assistance in calculating your travel life requirements click the Life Calculator button

The travel life default setting for all Thomson slides is 10,000,000 inches (255 km). To modify, unclick the check box and enter the desired value. Select the unit of measure from the unit selection box. A LIFE CALCULATOR button (noted below) will also appear for assistance in calculating a value based on known application requirements.



Travel life values below the default will not change the bearing capacities and will yield the same solution set of products as the default. Travel life values above the default cause the program to simulate a bearing capacity change by adjusting your application entries accordingly. This is done internally to the program and will not alter your original entries.

Life Calculator: This function is designed to assist in calculating Travel Life requirements.

Life Calculator * Distance moved per cycle	in	
Required cycles		
Number of cycles that must be completed each hour	0R-	Number of hours of operation per day
Days per week		Weeks per year
Years		
	Calculate Travel Life	Calculated Value :

Enter the distance moved per cycle and select the unit of measure from the unit selection box. Enter either a required number of cycles or an hourly number of completed cycles. After these values are entered in the appropriate fields, click CALCULATE TRAVEL LIFE. The calculated value appears in blue towards the right of your screen and is automatically entered in the Travel Life value box above.

To save current data to our database for future retrieval, click SAVE CURRENT DATA in the lower left of the screen. Refer to section 1.3 of this user guide for step-by-step instructions of the saving process. Click CONTINUE to proceed to Step 3 of the Sizing and Selection Process.

3.1.4 Environmental Condition (Step 3)

This screen identifies some of the most common environmental situations that may be encountered and provides option sets based on application environment. (For non-standard environmental conditions other than those shown, please contact our sales engineers for assistance at 540-633-3400).

O Clean	O Moderate to Heavy Dust Particulate Count	t 🔘 Water/Chemical Splash
○ Water/Chemical Spray/Fog	◯ High Pressure/Temperature Washdown	O Clean Room
Impact/Press App.Nibration		
engineers for more details.	ed to accommodate non-standard environmental cond ection, we recommend the following linear slide option	
Ball Guide Options :		
🔘 Standard Steel Ball Guide	🔾 Stainless Steel Ball Guide	Armoloy Plated Ball Guide
Chrome Plated Ball Guide	Raydent Surface Ball Guide	
Linear Bearing Options :		
🔿 Standard Linear Bearings 🕧	CR Linear Bearings	Polymer Plain Bearings
Hardware Options :		
Standard Hardware	Stainless Steel Hardware	
Cover Options :		
O No Cover	Bellows	Shroud
 Enclosed (ideal seal) 		
Lubrication Options :		
Standard Grease	Clean Room Grease	

3.1.4.1 Conditions: Select one of the environmental conditions from the bulleted list. To include all products in the solution set, select the CLEAN condition.

The CLEAN condition is broader in scope than a lab environment setting as it also encompasses a mild shop and production floor environment.

ň

3.1.4.2 Linear Slide Option Sets: Our system pre-selects options based on the environmental condition selected. System defaults may be modified to suit user requirements by clicking on appropriate bullets. Altering selections may change your solution set. The following tables are matrices describing the relationships between the environment conditions, the products, and the options available. Also refer to <u>Appendix A</u> for more information regarding product options.

Options/Environment	Clean	Moderate to Heavy Dust Count	Water Chemical Splash	Water Chemical Spray/Fog	High Pressure / Temperature Washdown	Clean Room	Impact/ Press App/ Vibration ***
Ball Guide Options							
Standard Steel Ball Guide	Х	Х	Х				Х
Stainless Steel Ball Guide	Х	Х	Х	Х	Х	Х	Х
Armoloy Plated Ball Guide	х		Х	Х	Х	Х	Х
Chrome Plated Ball Guide	х		Х	Х	Х	Х	Х
Raydent Surface Ball Guide	х		Х	Х	Х	Х	
Linear Bearing Options							
Standard Linear Bearings	Х	Х	Х			Х	
CR Linear Bearings			Х	Х	Х	Х	
Polymer Plain Bearings		Х	Х	Х	Х		Х
Hardware Options							
Standard Hardware	Х	Х	Х				Х
Stainless Steel Hardware		Х	Х	Х	Х	Х	Х
Cover Options							
No Cover	Х				Х	Х	Х
Bellows			Х				Х
Shroud			Х		Х	Х	Х
Enclosed (ideal seal)		Х	Х	Х	Х		Х
Lubrication Options							
Standard Grease	Х	Х	Х	Х	Х		Х
Clean Room Grease						Х	

***Impact/Press App/Vibration column does not apply for Vertical system orientations even though the condition can be selected. A message will occur with No Solution Available.



A green cell denotes the defaults when a condition is selected. A blank cell indicates the option is not available and will be grayed out on the Linear MOTIONEERING[®] screen.

Linear MOTIONEERING®

Options/Product Family

•			y			I	inea	r								
		Ва	ll Gui	de			earing		Hard	dware		Co	ver		Lubri	cation
	01	O2	O3	04	O5	06	07	08	09	O10	011	012	013	014	O15	O16
	Standard Steel	Stainless Steel	Armoloy Plated	Chrome Plate	Raydent Surface	Standard	CR	Polymer	Standard	Stainless Steel	No Cover	Bellows	Shroud	Enclosed	Standard	Clean Room
2DB	1	1	1	1	0	1	1	0	1	1	1	1	0	0	1	1
2EB	1	1	1	1	0	1	1	0	1	1	1	1	0	0	1	1
MS25	1	1	1	1	0	1	0	0	1	1	1	1	0	0	1	0
MS33	1	1	1	1	0	1	0	0	1	1	1	1	0	0	1	0
MS46B	1	1	1	1	0	1	0	0	1	1	1	0	1	0	1	0
MS46E	1	1	1	1	0	1	0	0	1	1	1	0	1	0	1	0
2RB	1	1	1	1	0	1	1	0	1	1	1	1	0	0	1	1
2RE	1	1	1	1	0	1	1	0	1	1	1	1	0	0	1	0
2HB	1	0	1	0	0	1	0	0	1	1	1	1	1	0	1	1
2HE	1	0	1	0	0	1	0	0	1	1	1	1	1	0	1	0
TF	1	2	0	0	0	1	2	0	1	1	2	2	2	1	1	0
TG	2	2	0	0	0	2	2	1	1	1	2	2	2	1	1	0
MF	1	2	0	0	0	1	2	0	1	1	2	2	1	1	1	0
MG	2	2	0	0	0	2	2	1	1	1	2	2	1	1	1	0
DS4/6	1	1	0	0	0	1	2	0	1	1	2	2	2	1	1	1
URS * Adjustm	1	0	2	2	1	1	0	0	1	1	1	0	1	0	1	1

* Adjustments in calculations will occur in order to accommodate for option fit.

0 – Option not available

1 – Option available

2 – Option not available but selection allowed. A pop-up caution note will occur upon selection of model as shown below:

WIIIdow	rs Internet Explorer 🛛 🛛 🔀
?	Standard Steel Ball Guide Standard Linear Bearings Options are not available for the selected solution, Do you want to continue?
	OK Cancel

3.1.5 Load Requirements (Step 4)

This screen requires load and applied force details. End supported or intermittently supported mounting configurations will require maximum support distance entries.



- Load: Enter the weight the carriage or saddle supports in the value box and select the unit of measure from the unit selection box. See <u>Appendix A</u> for more detail.
- Center of Gravity: Locate the center of gravity (or center of mass) of the load with respect to the center of the carriage/saddle (see diagram) and enter the value in the box. Enter the X, Y and Z values in the appropriate boxes and select the unit of measure from the unit selection box.



For Horizontal, Horizontal Side, and Inverted System orientations, the X-axis is considered the direction of travel. For the Vertical orientation, the Y-axis extends perpendicular to the face of the carriage while the X-axis is parallel to the face of the carriage.

• Applied Force: Enter the applied force in the value box and select the unit of measure from the unit selection box. The Applied or external force is independent of the load (process related forces) and is assumed to be exerted at the center of gravity (or mass) of the load with respect to the X, Y, Z coordinate system. The system defaults to an X-axis direction of force but can be changed to a Y- or Z-axis by selecting another value from the drop-down list box. Multi-axis applied force must be broken down into its axial components. See <u>Appendix A</u> for more detail.



A negative Applied Force Plane exerts the force toward the center of the Cartesian Coordinate graphic.



Deflection calculations include those generated by the Load and Applied Force (applied in the appropriate force plane). Additionally, deflections occurring from moment loading are considered.

 Clear Span, FSW, RSW: End supported mounting configurations require values for Clear Span, Forward Span Width, and Rear Span Width. Linear MOTIONEERING[®] calculates System Length in two ways: 1) the stroke entry is added to the combined width of the carriage and both end blocks, and 2) the combined total of the clear span with the FSW and RSW. Only the larger of the two lengths is considered for overall system length.

Max Distance	Applied Force 0.00 Ibf The Applied or external force is independent of the load (process related forces) and is assumed to be exerted at the center of gravity of the load with respect to the X,Y,Z coordinate system Direction of force x axis
	Max distance between any two adjacent supports

• Max distance between any two adjacent supports: Intermittently supported mounting configurations require entry of the maximum distance between any two adjacent supports.

To save current data to our database for future retrieval, click SAVE CURRENT DATA. Refer to <u>section 1.3</u> of this user guide for step-by-step instructions of the saving process. Click CONTINUE to proceed to Step 5 of the Sizing and Selection process.

3.1.6 Move Profile (Step 5)

This screen requires entry of travel distance, move, and dwell times to create an application-specific move profile.

- Distance: Enter travel distance. This value must be smaller than (or equal to) the stroke length entry of Step 3.
- Move Time: Enter move time value. See <u>Appendix A</u> for details on entering a segmented move profile.



- The Distance and Move Time values are not enough information to generate a move profile with a determined acceleration rate. The program will determine an acceleration rate range for each product based on this application data. These calculations also generate maximum and minimum velocities. You will have the opportunity to modify the acceleration rate to fit your application in Step 8.
- Dwell Time: Enter dwell time (i.e., the time the slide is completely at rest). Dwell time is used primarily for motor sizing duty calculations. If left at zero, Linear MOTIONEERING[®] will assume 100% duty cycle, which will also eliminate some lead screw driven units from the solution set. To assure both lead and ball screw units are a part of the solution set, the duty cycle must be 60% or less.

To save current data to our database for future retrieval, click SAVE CURRENT DATA. Refer to <u>section 1.3</u> of this user guide for step-by-step instructions of the saving process. Click CONTINUE to proceed to Step 6 of the Sizing and Selection process.

3.1.7 Parameter Review (Step 6)

This screen summarizes application entries and provides an opportunity to make changes.

Step 6 - Review Your Application Parameters Back Please review your application parameters. Click on any one you would like to change. Orientation **Positioning Requirements Envirnomental Condition** entation : Horizontal Condition : Clean Stroke Length : 1000.00 mm Ball Guide : Standard Steel Ball Gu.. Accuracy : No Preference Linear Bearing : Standard Linear Be Repeatability : No Preference Hardware : Standard Hardw Mounting Configuration Maximum Allowable Backlash : No Pr... Cover : No Cover 4 Configuration : End ! Travel Life : 10,000,000 in Lubrication :Standard Grease **Loading Conditions Move Requirements** Load : 2.00 lbf Distance : 2.00 in X Location : 0.00 in Move Time : 2.000 sec Y Location : 0.00 in Dwell Time: 0.000 sec . Z Location : 0.00 in Applied Force : 0.00 lbf Direction of Force : x axis Clear Span: 7.00 in FSW: 1.00 in RSW; 1.00 in Continue Please click Continue, when complete Privacy Statement | Site Disclaimer | About | Contact © Copyright 2000-2007 Danaher Motion. All rights reserved.

Click on any parameter to return to the relevant screen. Changes to 'Mounting Configuration' or 'System Orientation' require revisiting each remaining screen to modify previous entries. Otherwise, the user is returned directly to 'Parameter Review'. Click CONTINUE when review is complete.

3.2 Choose Your Solution

2077 U.V.

3.2.1 Review Solutions, Edit Requirements and Select System (Step 7)

This screen presents a list of systems meeting previously selected requirements sorted by price.

 Part Number	Bearing Load Safety Factor	Ball Screw Load Safety Factor	Ball Screw Critical Speed Safety Factor	Belt Tension & Anial Load Safety Factor	Base System Price **
MG058130A00X	40.9%	N/A	N/A	Exceeds 100x	\$ 1004.11
MG06K057A00X	42.3X	Exceeds 100X	2.8X	N/A	\$ 1381.97
MGD5K107A0DX	42.30	Exceeds 100X	5.7)(N/A	\$ 1381.97
MG06K207A00X	42.30	Exceeds 100X	11.000	N/A	\$ 1381.97
MG06KU57A00X	42.30	Exceeds 100X	2.5)(N/A	\$ 1381.97
MG068105A00X	42.3X	N/A	N/A	Exceeds 100X	\$ 1520.63
MG06C329A00X	42.3X	Exceeds 100X	15.7X	N/A	\$ 1679.66
TG05B130A00X	41.2X	N/A	N/A	Exceeds 100X	\$ 1695.49
TG06K659A00X	42.6X	Exceeds 100X	2.5X	N/A	\$ 1695.49

** The Base System Price reflects systems without accessories or special configurations defined in the preceding steps. Total pricing will be displayed on the next page

- Safety Factors Definition: A "1x" in a Safety Factor column indicates that the system is at performance capacity. Values above 1x provide the user with a relative value of how much capacity remains, should adjustments to application data need to be made. In most cases, values below 1x eliminate a product model from the solution set.
- Bearing Load Safety Factor: This value represents the total available safety margin for the most heavily loaded bearing in a given slide unit. It is plane specific and considers the results of static load, applied force and acceleration forces generated for appropriate planes and system orientations.
- Ball Screw Load Safety Factor: This value represents the total available safety margin that a ball screw or lead screw driven slide can sustain in an axial plane. Static load, applied force and acceleration forces are considered in the appropriate planes for a given orientation and then compared to radial bearing capacity (axial), ball nut capacity and column loading calculations. The lowest of these three capacities is used to calculate the safety factor.
- Ball Screw Critical Speed Safety Factor: This value represents the available safety margin as framed by the calculation that defines a Ball Screw's critical speed (the point at which it will begin to vibrate and whip [rotationally]. Contributing to this calculation are your requirements as entered in Step 5, the particular units length, lead, diameter and end bearing configuration.
- Belt Tension & Axial Load Safety Factor: This value represents the total available safety margin that a belt driven unit can sustain in an axial direction. Static load, applied force and acceleration forces are considered in the appropriate planes for a given orientation and then compared to that particular unit's Belt Pre-Tension value.

Pricing in this table reflects systems without accessories or special configurations. Select a system from the list and click CONTINUE. There will be opportunities to refine your choice further on the next screen.

3.2.2 Review Your System Specifications (Step 8)

This section of the user guide is arranged by model group based on differences in motor types, slide accessories and pricing associations (refer to the flowchart in <u>section 2.3</u> for a visual breakdown). Each group has in common a system profile chart based on the user's application entries and the product's performance parameters. To the left of the chart appear the numerical values and ranges from which the chart plots were created. You may choose to vary the acceleration rate to any point within the range and the system plot will change accordingly.

e Appendix B for rt Number Description	2DB08C0N0320-200N001A0A00 Satalog Data	Continuously Su Bass with sector ran rane is a first in tetechol	aperted Ball Screw Driven System Adistryou system. I Prefers, exchapter of specifications.
TetalPrice: \$ 1847 (D)	 Used in continuously supported application when rightly a required. Preval generating development of the immediate/installation and use. Desagned tait machamic behaviory loads. Issegned at an accurate how one mail youth statistical MEMA/meter maching. 	 SperType Inske Inske Inske Sperkoad, Systel, Length Y.Dimension Meter ID 	Norm Club Fore South Fore South Fore South Fore South Fore South South South
List pricing shown is far the une of authorited North	Please slick Select Motor Adaptor, to condu		Gelect Motor Adaptor
Minite EVelasion schedule. Minite Parameters Bios a spacific vocation for and the mass parties will be updated accordingly. Acceleration Rate (m/s?) 1,4322 4.636 7.8400 Update Speed (m/s) 0.3242 0.3292 0.3837	0.39 0.36 0.33 0.30 0.27 0.27	Move Profile	
Safety Factors Bearing Load 9.3X Bell Screw Load 1.7X Ball Screw Critical Speed 1.1X	0.24 0.21 0.18 0.12 0.12 0.06		
	0.03 6.00 0 0 Buil using 0	j 1me(sec) harFX tor AET Develop	2

3.2.2.1 2DB, 2EB, 2HB, 2RB, 2HE, 2RE, MS25, MS33, and MS46 Models

3.2.2.1.1 Pricing

For this group of products the total price shown on the screen will update as options are selected (see next point). Motor adapter selections are not included in this total price. Contact Thomson Customer Service (540-633-3400) for motor pricing information.

3.2.2.1.2 Options

Selections can be made from the drop-down lists to the right. A grayed drop-down list indicates that no options are available under that heading for your environmental and application conditions or that there is only one option available and the selection in mandatory. Clicking on active option headings will open an Adobe pdf file in a separate window of the technical specifications.



In most cases the System Length will vary somewhat from your application entries by a factor of the Y-Dimension (click to see the Y-Dimension diagram). Linear MOTIONEERING[®] will adjust the overall length to ensure that the last pair of mounting holes is usable. Refer to <u>Appendix A</u> for more information.

3.2.2.1.3 Motor Sizing Information

For users not selecting a standard optional motor listed in the Select Motor Adapter section, Linear MOTIONEERING[®] will calculate performance requirements needed for any selected motor based on user application data. To access this feature, scroll down and click the button in the bottom left corner of the screen. Contact Thomson Customer Support (540-633-3400) for further assistance in customer motor sizing.

3.2.2.1.4 Motor Adapter

This feature allows the user to select a motor from a list of predetermined motors or to enter specific values for a customer-supplied motor (refer to <u>Appendix A</u> for more detail).

Motor Manufacturer	NEMA 17	Motor Pa	nt Number:	NEN	IA 17
If the manufacturer	and part number are n	ot found, requirements can be e	ntered man	ually	Enter Motor & Dimensions
Motor Manufacturer:	NEMA 17	Pilot Diameter:	21-97606	mm	(B.8 to 53.2 mm)
Motor Part Number:	NEMA 17	Pilot Length:	2.83200	mm	(0 to 3.5 mm)
		Shaft Diameter:	5:00202	mm	(2.8 to 13.2 mm)
	(Shaft Length:	21.97100	mm	(127 to 34.29 mm)
		Bolt Circle Diameter:	43 B4040	mm	(19.8 to 70.2 mm)
		Bolt Circle Thru Hole Dia: or	0.02540	mm	(0 to 6.2 mm)
		Bolt Circle Threaded Hole Size:	4-40 -		

- Select the manufacturer and part number from the drop-down list boxes. The motor and dimensions will appear as grayed values in a list. Click FINISH to complete the process.
- To manually enter values, click ENTER MOTOR AND DIMENSIONS. After all information is entered click VERIFY.



Data must be verified in order to be saved. Saved motor data is not considered application data and will only be retained for your current working session. It will not be saved with the application information.

3.2.2.2 DS4/DS6 Models



3.2.2.2.1 Pricing

For this group of products the total price shown on the screen will update as options are selected (see next section).

3.2.2.2.2 Options & Accessories

Selections can be made from the drop-down list to the right. A grayed drop-down list indicates that no options are available under that heading for your environmental and application conditions. Clicking on active option headings will open a pdf file of the technical specifications in a separate window.

Clicking this icon will pull up a list of available motors, motor mounts, and couplings.

3.2.2.2.3 Motor Sizing Information

For users not selecting a standard optional motor, Linear MOTIONEERING[®] will calculate performance requirements needed for any selected motor based on user application data. To access this feature, scroll down and click the button in the bottom left corner of the screen. Contact Thomson Customer Support for further assistance in customer motor sizing.

3.2.2.3 TF/TG, MF/MG Models



3.2.2.3.1 Pricing

For this group of products the slide table total price shown on the page will not update as Accessories & Options are selected. The printable application page available at the end of the selection process lists both the slide unit and accessory (per unit) pricing in an itemized format. Contact Thomson Customer Service (540-633-3400) for motor pricing assistance.

3.2.2.3.2 Options & Accessories

Click the MotorMount & Accessories button to see a page of options and accessories. The number of options available will vary based on the selected unit within this grouping. Make selections by checking boxes or selecting an item from a drop-down list box. Descriptions can be reviewed by clicking a next to the name of each option. A grayed drop-down list or empty box indicates that no options are available under that heading.

3.2.2.3.3 Motor Sizing Information

Linear MOTIONEERING[®] will calculate performance requirements needed for any selected motor based on user application data. To access this feature, scroll down and click the button in the bottom left corner of the screen. Contact Thomson Customer Support for further assistance in customer motor sizing.

3.2.2.4 URS20 – URS55 Models



3.2.2.4.1 Pricing

For this group of products the total price shown on the screen will update as options are selected (refer to next section).

3.2.2.4.2 Motor Sizing Information

For users not selecting a standard optional motor, Linear MOTIONEERING[®] will calculate performance requirements needed for any selected motor based on user application data. To access this feature, scroll down and click the button in the bottom left corner of the screen. Contact Thomson Customer Support for further assistance in customer motor sizing.

3.3 View and Download System Models - Refer to Section 6.1

4 Configuration and Quoting

4.1 Select Product Family

Select product family from the list and click CONTINUE.

4.1.1 Select the System you wish to configure

This screen requires the user to enter a system length and either choose a system from the list presented or change the original system selection.

Select the System you wish to configure



 Part Number	Old Part Number	Actuation Type		Shaft Way Diameter / Profile Rail Way Width	Max Length	Gear Ratio	1
20808A0	208-08-0UB-AA-		See <u>Appendix B</u> for Part Number Description	0.50 n	48 In	N/A	1
2D80880	2DB-08-0UB-AB	LeadScrew		0.50 in	48 in	N/A	
2080800	208-08-0UB-AC	LeadScrew	0.375in x 0.50in P	0.50 in	48 in	N/A	
2080800	208-08-0UB-AD	LeadScrew	0.375in x 0.75in P	0.50 in	48 in	N/A	1
2DBDBE0	2DB-08-OUB-AE	LeadScrew	0.375in x 1.00in P	0.50 n	48 in	N/A	A.S.
2DB12B0	2DB-12-0UB-B	BallScrew	12mm x 5mm NP	0.75 in	72 in	N/A	
2DB128K	208-12-0UK-B	BallScrew	12mm x 5mm NP	0.75 in	48 in	N/A	
2DB12F0	208-12-008-F	BallScrew	0.500h x 0.200h NP	0.75 in	72 in	N/A	
2DB12QJ	208-12-JUB-Q	BallScrew	0.500 n x 0.500 n P	0.75 n	72 in	N/A	

Select a system and click continue Continue

- Enter system length in the value box (if available).
- Select one system from the list presented.
- If the desired system does not appear in the table, choose a different product family from the dropdown list box. Choosing a different family requires re-entry of system length after Linear MOTIONEERING[®] refreshes the system list.



System length requirements may not exceed the maximum length of your selected system.

Click CONTINUE to configure your system.

- 4.1.2 Configure your System or select a different system refer to section 5
- 4.1.3 View and Download System Models refer to section 6.1



A Back

Or, Lookup by Part Number

Specify System Length 0.0



If you have an old part number (i.e. 2DB-12-0UB-L12), please use your back button to return to the main screen, and then use the "Select a Product Family" option to locate your part number.

Enter your part number using the new part numbering system (i.e. 2DB08C0N0120-200N001A0A00), then click PARSE PART NUMBER. Linear MOTIONEERING[®] will parse the part number to confirm. The part number may then be modified with respect to options and accessories by selecting other options from the drop-down list boxes. Once the part number is correct click VERIFY AND CONTINUE.

5 Configure your System or select a different system

This screen displays a list of features for your chosen system. Systems may be modified to accommodate specific environmental conditions. Users may select from available cover types, brakes, limit switches and gearheads. Cost of the various elements of your system is displayed and catalog data is available. System length may be changed or a different system selected.

- Conditions: Refer to <u>section 3.1.4.1</u> of this user guide. For details regarding custom options available for environmental conditions refer to <u>Appendix C</u>.
- Linear Slide Option Sets: Refer to <u>section 3.1.4.2</u> of this user guide.
- For 2DB, 2EB, 2HB, 2RB, 2HE, 2RE, MS25, MS33, and MS46 Models, refer to section 3.2.2.1 for further direction.
- For DS4/DS6 Models, refer to section 3.2.2.2 for further direction.
- For TF/TG, MF/TG Models, refer to <u>section 3.2.2.3</u> for further direction.
- For URS20 URS55 Models, refer to section 3.2.2.4 for further direction.

6 Further Support

6.1 3D CAD Model

This screen offers several options to print or view your system.



- Linear MOTIONEERING[®] allows the model to be viewed from all angles. Click the picture of your system to activate the control. Left click and drag to rotate the image. Right click and move mouse up or down to resize the image. To relocate the image on the screen, click and hold both mouse buttons and drag the image to the new location.
- Downloads are available in many formats and software versions.

Click FINISH to exit screen.

6.2 Request a Quote

6.2.1 Login ID Required

- To acquire a login ID, refer to <u>section 1.3.1</u> of this user guide for instructions.
- Users with login IDs may login at this point. Refer to section 1.3.1 of this user guide for instructions.
- If you are already logged in you will not be required to do so again.

6.2.2 Request a Quote Screen

- The top section of this screen displays user selected specifications and accessories.
- The bottom section of this screen displays contact information for review and correction. Include a comment or additional details in the Comment box.



Information in yellow boxes is required. Changes to this information will not change user profile. Please refer to <u>section 1.3.2.1</u> of this user guide for instructions on editing your user profile.

- Click SUBMIT to send in your quote request. Linear MOTIONEERING[®] will open the 'Further Support' screen and provide a screen confirmation that a quote request was submitted. An email confirmation with details of the quote request will be sent to the contact email address.
- Linear MOTIONEERING[®] will generate and email a date stamped, sequence numbered quote valid for 90 days. A duplicate of this email will be forwarded to the Thomson Assistance Center. Please contact the Assistance Center at 540-633-3400 to place your order.

6.3 Printable Application Page

This button opens a printable specifications page for the configured system. To return to the previous screen, click either the Back button of your browser or BACK on the Linear MOTIONEERING[®] screen.

6.4 Save Application

If this option is grayed the application may not be saved. Otherwise, refer to <u>section 1.3</u> of this user guide for a description of the saving process.

6.5 Exit Motioneering

Click here to exit Linear MOTIONEERING[®] and close your browser window. Before exiting, Linear MOTIONEERING[®] will prompt the user to save the current application. Clicking SAVE requires the user to log in (refer to <u>section 1.3</u> of this user guide for instructions). Clicking CANCEL exits Linear MOTIONEERING[®] and closes your browser window.

7 Appendices

7.1 Appendix A: Frequently Asked Questions

General

- **How do I get started?** Linear MOTIONEERING[®] is divided into two modules; "Sizing and Selection" and "Configuration and Quoting". If you already know the Thomson Slide Table you need, choose the "Configuration and Quoting" module to get additional information (pricing, 3D models, etc). Otherwise, use the "Sizing and Selection" module for help in specifying the correct product for your application.
- What products are included in the software? The application includes the following product families:

iunnioo.			
2DB	2EB	2RB	TG
2RE	2HB	2HE	TF
MS25	MS33	MS46	MG
DS4	DS6	URS	MF

I have an old Thomson part number (i.e. 2DB-08-0UB-AAL18). Can I get more information on this system? Pricing, 3D models, accessories, and other information is available through the "Configuration and Quoting" module of Linear MOTIONEERING[®]. Choose the "Select a Product Family" option, located on the bottom-right portion of the home page, and then press "Continue". Use the information found on this page to locate your old Thomson part number. The following systems now come standard with a RediMount[™] motor adapter block and coupling. The RediMount[™] feature allows you to mate our systems to most motors with no increase in lead-time or pricing.

2DB	2EB	2RB
2RE	2HB	2HE
MS25	MS33	MS46

• I have a new Thomson part number (i.e. 2DB08A0N0180-300N001A0A00). Can I get more information on this system? Pricing, 3D models, and other information is available through the "Configuration and Quoting" module of Linear MOTIONEERING[®]. Choose the "Lookup by Part Number" option, located on the bottom-right portion of the home page, and then press "Continue". Enter your entire part number (including the "-") and then press "Parse Part Number". If your part number is valid, you will be prompted to continue. For more information please see <u>Appendix B</u> of this document.

Positioning Requirements

- My application requires limit switches. What accommodations must be made in my stroke length? Generally speaking, should a limit switch go active a properly sized motor and control package will decelerate the load in less than two revolutions of the motor shaft (direct couple). With that said, extend your stroke a minimum of 4x the lead of the ball or lead screw. It's understood that at this point in the sizing software the systems and their associated leads are not known, therefore estimate. Assume 2-3" initially and then refine your system length after slide table selection.
- How do you define Accuracy? Accuracy is defined as the maximum error realized between an expected and actual position. It is the result of an accumulated lead error (ball screw or belt drive mechanism) over any 300 mm length along the linear guide track. In the case of Linear MOTIONEERING only the mechanical drive component(s) contained within the linear slide is taken into account. Motor resolution, encoder resolution, coupling compliance or lash and other drive related accessories are not considered in this callout. (For example: on an Accuracy call out of .127 mm /300mm; a 3000 mm ball screw driven slide will have, <u>over its entire stroke</u>, an Accuracy of 1.27 mm. However, over <u>any</u> 300 mm of length it will be .127mm).

- How do you define Repeatability? Repeatability is defined as the ability of a positioning system to return to a location during operation when approaching from the same direction (at the same speed and deceleration rate). Again, Linear MOTIONEERING[®] only considers the mechanical components within the linear slide system. Angular repeatability of the motor, encoder resolution or any other external device which contributes or reports positional information is not considered.
- How do you define Maximum Allowable Backlash? Maximum Allowable Backlash is defined as the total amount of play (lost motion) between the drive components of the linear slide. External drive mechanisms, including motors and mechanical brakes, are not considered by Linear MOTIONEERING[®].

Environmental Considerations

- What is an "Armoloy" Plated Ball Guide? Armoloy is a proprietary process that deposits a thin dense chrome coating onto the linear guides and is offered as an option for the majority of Thomson Linear slides. It exhibits exceptional corrosion resistance and attains a hardness of 78Rc. This proprietary process is licensed by the Armoloy Corporation.
- What is "Raydent" Plated Ball Guide? Raydent is a proven, precisely applied thin rust-preventing film. The surface treatment has exceptional durability (greater than 10 years), and any fine grains of Raydent that do break away from the contact between the rail and the recirculating balls will actually add to the lubricity of the grease.
- What is a "CR" Linear Bearing? The "CR" stands for Corrosion Resistant. This bearing option contains 400 series ball bearings supported by chrome plated bearing plates. This combination coupled with the polymer bearing retainer gives this linear bearing exceptional corrosion resistance in harsh environments.
- What is a "Polymer Plain Bearing"? In some of our product families plain Polymer linear bearings are installed in lieu of the standard re-circulating linear ball bearing. These are sliding linear bearings with low friction. They are excellent in high vibration, mechanical shock and wash-down applications.
- What is an "Enclosed, Ideal Seal"? The enclosed or ideal seal is offered as a standard feature on Rapid Track, MovoPart and DS Series units. It consists of a magnetic cover strip that seals the belt or ball screw from contaminates by completely enclosing the unit. The strip remains stationary while ramp features on each side of the saddle gently lift and subsequently replace the strip as linear motion is initiated.

Loading Information

- The load in my application is not mounted to the face of the carriage but instead to the base (the carriage is the fixed element). Can I use Linear MOTIONEERING[®] to help in selecting a Slide Table? It is slightly more complicated to size an application where the load is not fixed to the face of the carriage. The key consideration will be moment loading on the bearings, which will change as the base traverses. Linear MOTIONEERING[®] can be very helpful in selecting the right product for these types of applications; however, additional calculations will be required. Contact sales engineering at the Thomson Assistance Center (540) 633-3400 for more assistance.
- Why can't I enter negative values when locating my load with respect to the carriage? The bearing geometry within the carriage assembly is symmetrical in two loading planes (the third represents direction of movement for the bearing). In addition, the acceleration and deceleration rates generated in the move profile are calculated as the same. With this in mind, positive values are all that are required to represent load location.
- What is an Applied Force? The applied force is any factor, other than the load mounted to the carriage, exerting a force in your application. A common example would be the force exerted by a drill-bit in a drilling operation. Linear MOTIONEERING[®] assumes that the applied force is exerted at the center of mass of the load.
- What's the naming convention for Direction of Applied Force? Positive values are represented by the arrow vectors in the load diagram. A value with a positive Z assignment reflects an Applied Force acting against gravity (up).

• My Applied Force is not exerted at the center of mass of my load. Can I use Linear MOTIONEERING[®] to help in selecting a Slide Table? Linear MOTIONEERING[®] can accommodate this in two ways. First, if your applied force is significantly greater than the force due to the load on the carriage, you can make a reasonable approximation by using the "X", "Y", and "Z" inputs to reflect the location of the Applied Force. Or, to accommodate both forces, you can manually calculate a single resultant force and location, and use this as the input for the Applied Force and the XYZ inputs.

Enter Your Move Profile

• My move profile is comprised of several segments. Can I use Linear MOTIONEERING[®] to help in selecting a Slide Table? Yes, but there are a few things to keep in mind. Remember, we're sizing a mechanical system here first, so the most aggressive move segment associated with the entered Load/Applied Force values is what we need. However, there may be other move segments in your application which are lightly loaded but run at higher speeds (rapid feeds or rapid returns). In these cases wait until you get to Step 7, then, multiply the Ball Screw Critical Speed Safety Factor by the Linear Speed shown. The product is the highest linear speed this slide table can accommodate. Compare it with your requirement. If your requirement is lower, you're OK. If not, go back a step and find a system with a higher B/S Critical Speed Safety Factor or consider lowering the application requirement. Linear MOTIONEERING[®] only requires the most aggressive segment of your move profile to size the proper Slide Table. Enter this information as your "Distance" and "Move Time". Remember: Linear MOTIONEERING[®] later provides information for motor sizing/selection. Since this data will be based solely on this one segment of your profile, be sure to confirm higher unloaded speeds meet with your motor requirements.

Review Application Parameters

• I'd like to change one of my application parameters. How do I go back? You can go directly to the page where this parameter is entered by placing your cursor directly over the parameter displayed on this screen, and clicking your mouse button. Remember: Changes made to "System Orientation" and "Mounting Configurations" in Step 1 will require you to confirm all your entries for the succeeding steps.

Review the Solutions that Satisfy Your Application

- I see several Slide Tables on this screen. Which one should I choose? Linear MOTIONEERING[®] has filtered through the entire offering of Thomson Slide Tables and displayed each system that can meet the needs of your application. The systems were then sorted by price, displaying the most economical solution at the top of the list. Pay careful attention to other factors (screw lead, safety factors, available accessories) which may also play into your decision.
- What do the safety factors tell me? A safety factor of 1x means you're at capacity for that particular system parameter. Values above 1x represent excess capacity (a good situation) while values below 1x reflect system parameters that fail to meet the application requirements.
- How do I get more information about a Slide Table on the list? General information (screw lead, features and benefits, available accessories) can be accessed from the "Step 7" main screen simply by clicking on the appropriate row in the table. The row will be highlighted in green, and the information displayed on the screen will be updated. For more detailed information (3D models, pricing on accessories, request a quote); highlight the appropriate row, and then click the "Continue" button located in the bottom right corner of the screen.

Review Your System Specifications

• The "Cover Type" option is not available. How do I add bellows or a shroud cover to this system? The option to add bellows was available in Step 3 of the Environmental Conditions section. To add bellows at this point, click the "My Applications" link on the top tool bar; then click on the "Bellows Required" link, found under the heading "Specifications". On this screen choose the "Bellows Required" option. IMPORTANT!! You must then click "Continue" and then "Continue" again on the following screen.

- How do I get to CAD models? The 3D CAD Model tab on the navigation bar will only become active after a motor adapter has been selected from Step 8. Once the motor adapter has been identified, access to 3D and 2D CAD models in several formats becomes available (a login is required).
- I'd like a formal quote showing lead-times and any applicable distributor discounts off list pricing. How can I get this information? There are two options. You can select the "Request a Quote" option from the toolbar at the top of this screen (you may be required to login before gaining access to this feature); or, you can call customer service (540-633-3400) with your part number for assistance. Keep in mind that the "Request a Quote" tab on the navigation will only become active after a motor mounting block has been identified in Step 8.
- What is a "Y-dimension"? Can this dimension be changed? The "Y-dimension" represents a critical parameter for the base mounting hole pattern on Slide Tables. It represents the distance between the motor endplate and the first mounting hole. Click on the "Y-dimension" link for drawings showing this feature on our systems. There is a default "Y dimension" for each of our systems; however, adjustments must be made in circumstances where the default "Y" would result in a cut hole on the support end of the slide table. Linear MOTIONEERING[®] will provide a valid "Y Dimension" for all our systems. If your application requires a mounting hole pattern that differs from what is suggested, please contact sales engineering at (540-633-3400) for assistance.
- I've never seen a part number like this before...what does it mean? Why did you change? The development of Linear MOTIONEERING[®] created an opportunity to improve our part numbering system. In the past a customer ordered a slide and its accessories (motor adapter block, coupling, limit switch, etc.) with different part numbers on separate line items. For the complete package, the customer needed several part numbers. Also in the past, many common slide options (i.e. corrosion resistant bearings or stainless steel hardware) were considered non-standard, requiring a special part numbers. Slide tables and accessories configured using Linear MOTIONEERING[®] have been consolidated into a single 24-digit part number defining the slide and all its accessories. This will remove any potential confusion on whether accessories are to be provided attached to the slide or loose in the box. If the single part number is defined to include accessories then you know the complete unit will be delivered fully assembled. This also makes reordering a slide and its accessories quite simple. The single part number printed on the slide defines everything needed to reorder. For more information please see <u>Appendix B</u> of this document.

Change Motor Adapter

• I just want to order a Thomson Slide Table that I've ordered before. Why do you need information about my motor? The following systems now include the new RediMount[™] style motor adapter block and coupling (in the past, some of our slides came with NEMA standard motor adapter blocks and couplings, some came with nothing at all).

2DB, 2EB, 2RB, 2RE, 2HB, 2HE, MS25, MS33, MS46

RediMount[™] allows our slides to be easily mounted to a variety of motors, not just NEMA standards. To make this work, we'll need information about the motor that will be mounted to the slide. You can choose the default RediMount[™] (which will work with a standard NEMA motor); or you can provide us with the requested mounting information specific to your motor (pilot diameter, pilot length, etc.); or you can contact a sales engineer (540-633-3400) with your motor manufacturer name and part number and let us find the motor specific information for you.

• I entered my motor information but got a "999" in the part number. What does this mean? A "999" in the part number means that we can mate to your motor with RediMount[™], but we have not yet assigned a specific motor id. When placing an order, you will need to again provide your motor dimensions; we will assign a specific motor id and update your part number. Note that your pricing and lead-time will not be affected by these changes.

7.2 Appendix B: Part Number Description TG/TF/MG/MF Part Number Description

Please enter your part number :

MG06KU57C20X170

After you've entered your part number, it will be broken down into components.



Version	Profile Size (mm)		Drive Type / rive Specifics	Saddle Configuration	Screw Support Shaft Drive Option	Length (cm)
MF	05 (50mm)	B: Belt Drive	105: 105mm per rev, Belt	A00 (Standard Single)	X – No Screw Support	
MG	06 (55mm)	C: Ball Screw	130: 130mm per rev, Belt	C20 (Double, 20cm)	S – Single Support	XXX
TF	07 (75mm)	w/Composite Nut	176: 176mm per rev, Belt	C25 (Double, 25cm)	D – Double Support	
TG	10 (100mm)	D: Ball Screw	057: B/S 16mm x 5 NP	C35 (Double, 35cm)	R – Shaft Right	
		w/Double Nut	107: B/S 16mm x 10 NP	Cxx (Lc entry in mm)	Q – Shaft Left	
		K: Ball Screw	109: B/S 25mm x 10 NP	xx custom length	X – Shaft both sides	
		w/Ball Nut	129: B/S 19mm x 12.7mm NP			
			207: B/S 16mm x 20mm NP			Wash
			207: B/S 20mm x 20mm NP			Down
			208: B/S 16mm x 20mm NP			None
			257: B/S 25mm x 25mm NP			S1
			259: B/S 25mm x 25mm NP			S2
			329: L/S 16mm x 32mm NP			
			659: B/S 16mm x 5.08mm NP			
			729: B/S 19mm x 12.7mm NP			
			U57: B/S 16mm x 5.08mm NP			

Note: part # definition is solely for identification. Do not use to configure a system - for not all combinations are possible.

* S1 – Wash Down Protection, S2 – Chemical Protection

DS4 / DS6 Part Number Description

Please enter your part number :

DS450C10GX23OE4L0H0E0

After you've entered your part number, it will be broken down into components.

Family	Travel	Grade	Ballscrew Lead	Motor	Coupling/ Orientation Limits and Pulley	Home	Shaft Option	Linear Encoder	Additiona options
DS4	50 💌	C 🗸	10G 💙 🛛	X23 🗸		H0 💌	None 💌	E0 💌	None 💌

Family	Travel (mm)	Grade *	Ballscrew Lead	Motor Or Motor Mount **	Coupling Orientation and Pulley**	Limits	Shaft Option
DS4	50	С	5G (5mm)	X16		L0 - No Limits	Blank
DS6	100	Р	10G (10mm)	X17		LN1 - Limits, NPN type NO	BS Brake on ballscrew
	150		25G (25mm)	X23		LN2 - Limits, NPN type NC	24VDC Power-off
	200		. ,	X34	See	LP1 - Limits, PNP type NO	ES Rotary encoder on ballscrew
	250			X70	Page Below	LP2 - Limits, PNP type NC	1250 line
	300			P21	U U		
	350			T22T		Home	Linear Encoder
	400			T22V		H0 - No Limits	E0 No linear encoder
	450			T32T		HN1 - Home, NPN type NO	E1 1 micron res linear encoder
	500			T32V		HN2 - Home, NPN type NC	E2 0.5 micron res linear encoder
	550			BK23		HP1 - Home, PNP type NO	E3 0.1 micron res linear encoder
	600			BK23B		HP2 - Home, PNP type NC	
	700			BK23S			
	800			BK23SB			Additional Options
	900			BK32			P1 Std Pinning of x-axis carriage
	1000			BK32B			CLN Cleanroom Prep – Class 100
	1250						•
	1500						
	1750						
	2000						

Note: part # definition is solely for identification. Do not use to configure a system - for not all combinations are possible.

* C – Commercial, P – Precision

** Details on following page

Code	Description
X16	1.6" Frame Mount
X17	NEMA 17 Frame Mount
X23	NEMA 23 Frame Mount
X34	NEMA 34 Frame Mount
X70	NEO 70mm Frame Mount
P21	Stepper motor, 23 Frame
T22T	Stepper motor, 23 Frame wired in series
T22V	Stepper motor, 23 Frame wired in parallel
T32T	Stepper motor, 34 Frame wired in series
T32V	Stepper motor, 34 Frame wired in parallel
BK23	Brushless servo motor, 23 Frame with 2048 line encoder
BK23B	Brushless servo motor, 23 Frame with 2048 line encoder & brake
BK23S	Brushless servo motor, 23 Frame with SFD feedback
BK23SB	Brushless servo motor, 23 Frame with SFD feedback and brake
BK32	Brushless servo motor, 34 Frame with 2048 line encoder
BK32B	Brushless servo motor, 34 Frame with 2048 line encoder & brake

DS4 / DS6 Motor & Motor Mount Part Number Identifiers

DS4 / DS6 Coupling or Orientation/Pulley Bore Part Number Identifiers

Coup	ling	Orientation & Pulley Bore				
XC - No Coupling		(blank) - Inline Model (n/a)				
Oldham Couplings:	Bellows Couplings:	PRxx * - Parallel Right ⁹				
OE3 - 3/16" shaft	BE3 - 3/16" shaft	PLxx* - Parallel Left ⁹				
OE4 - 1/4" shaft	BE4 - 1/4" shaft	Puxx* - Parallel Under ⁹				
OE5 - 5/16" shaft	BE5 - 5/16" shaft					
OE6 - 3/8" shaft	BE6 - 3/8" shaft	* Select pulley bore below.				
OE8 - 1/2" shaft	BE8 - 1/2" shaft	xx3E - 3/16" Pulley Bore				
OE10 - 5/8" shaft ⁸	BE10 - 5/8" shaft ⁸	xx4E - 1/4" Pulley Bore				
OE12 - 3/4" shaft ⁸	BE12 - 3/4" shaft ⁸	xx5E - 5/16" Pulley Bore				
OM5 - 5mm shaft	BM5 - 5mm shaft	xx6E - 3/8" Pulley Bore				
OM8 - 8mm shaft	BM8 - 8mm shaft	xx8E - 1/2" Pulley Bore				
OM9 - 9mm shaft	BM9 - 9mm shaft	xx10E - 5/8" Pulley Bore				
OM11 - 11mm shaft	BM11 - 11mm shaft	xx5M - 5mm Pulley Bore				
OM14 - 14mm shaft ⁸	BM14 - 14mm shaft ⁸	xx8M - 8mm Pulley Bore				
OM19 - 19mm shaft ⁸	BM19 - 19mm shaft ⁸	xx9M - 9mm Pulley Bore				
		xx11M - 11mm Pulley Bore				
		xx14M - 14mm Pulley Bore				

URS Part Number Description

Please enter your part number :

URS3305D150BK22

After you've entered your part number, it will be broken down into components.

Base Unit URS33	BallScrew Carriage Lead Type 05 V D V	Length	None	e 🕶 🛛 E	Motor Or lotorFlange	Cover Option None	Sensor OptionSurface & lube OptionNoneNone		
Base Unit	Screw Lead	Rail Length	Grade*		or Flange **	Cover Option	Sensor Option		
JRS20 - 20mm x 40mm JRS26 - 26mm x 50mm JRS33 - 33mm x 60mm JRS46 - 46mm x 86mm JRS55 - 55mm x 100mm	01 (1mm) 02 (2mm) 05 (5mm) 10 (10mm) 20 (20mm)	100 150 200 250 300 400 500 600 340 440 540	None P	X16 T32T X17 T32TEN X23 T32TEN X34 K T12 T32V T12EM T32VEN T12EMK T32VEN T12EMK T32VEN T22T K T22TEM BK11 T22TEMK BK22		None H	None S – Set of 3 adjustable limit & home sensors		
	Carriage Type A (Std. Single) B (Std. Dual) C (Single Short) D (Dual Short)	640 740 840 940 980 1080 1180 1280 1380		T22V T22VEM T22VEMK	BK22B BK22S BK22SB BK32 BK32B		Surface & Lube Option None GK – Cleanroom Low Particulate RD – Raydent treatment Of rail surfaces GKRD – combination		

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Note: part # definition is solely for identification. Do not use to configure a system - for not all combinations are possible.

* C – Commercial, P – Precision

** Details on following page

URS Motor & Motor Flange Part Number Identifiers

Motor Mounts	Motors
X16	Motor flange for 16 Frame motor
X17	Motor flange for 17 Frame motor
X23	Motor flange for 23 Frame motor
X34	Motor flange for 34 Frame motor
T12	Stepper motor, 17 Frame
T12EM	Stepper motor, 17 Frame with 500 line encoder
T12EMK	Stepper motor, 17 Frame with 1000 line encoder
T22T	Stepper motor, 23 Frame wired in series
T22TEM	Stepper motor, 23 Frame wired in series, with 500 line encoder
T22TEMK	Stepper motor, 23 Frame wired in series, with 1000 line encoder
T22V	Stepper motor, 23 Frame wired in parallel
T22VEM	Stepper motor, 23 Frame wired in parallel, with 500 line encoder
T22VEMK	Stepper motor, 23 Frame wired in parallel, with 1000 line encoder
T32T	Stepper motor, 34 Frame wired in series
T32TEM	Stepper motor, 34 Frame wired in series, with 500 line encoder
T32TEMK	Stepper motor, 34 Frame wired in series, with 1000 line encoder
T32V	Stepper motor, 34 Frame wired in parallel
T32VEM	Stepper motor, 34 Frame wired in parallel, with 500 line encoder
T32VEMK	Stepper motor, 34 Frame wired in parallel, with 1000 line encoder
BK11	Brushless servo motor, 16 Frame with encoder
BK22	Brushless servo motor, 23 Frame with encoder
BK22B	Brushless servo motor, 23 Frame with encoder & brake
BK22S	Brushless servo motor, 23 Frame with SFD feedback
BK22SB	Brushless servo motor, 23 Frame with SFD feedback and brake
BK32	Brushless servo motor, 34 Frame with encoder
BK32B	Brushless servo motor, 34 Frame with encoder & brake

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2DB, 2EB, 2HB, 2HE, 2RB, 2RE, MS25, MS33, MS46 Part Number Description

Please enter your part number : 2DB12BKN0250-300N001A0A00

After you've entered your part number, it will be broken down into components.

Family	Engineering Designate	System Length	Y Dimension	Brake	Motor ID	Shafting	Bearing	Bellows Designate	Hardware Designate	Home/Limit Designate
2DB12BK	N	0250	300	N	1	A	0 💌	Α 🕶	0 🗸	0 🗸

Family* Screw	Eng	System Length	Y Dim** 200=2in	Brake	Motor ID	Shafting	Bearing	Home/Limit
2DB08xx	E	2DB, 2EB	200	N –	XXX	A - 60 Case	0-Std	0 - None
2DB12xx	Ν	XXXX	300	no brake	Contact	(1566)	1-Corrosion	1 - NPN, Home
2DB16xx		0250 = 25in		В –	Factory for	B - Stainless Steel	Resistance	2 - NPN, End of travel
2EB08xx			Y Dim**	w/brake	motor ID	(440C)		3 - NPN
2EB12xx			75mm=075		listing	C - Chrome Plated	Bellows	Home & End of travel
2EB16xx		All other units	039		Ū	E - Armoloy	A-none	4 - PNP, Home
2EB24xx		XXXX	050			E - Duralloy Coated	B-bellows	5 - PNP, Ends of travel
2HB10xx		0300=300mm	082			(2HB only)	C-shroud	6 - PNP
2HB20xx			075					Home & End of travel
2RB12xx			100				Hardware	7 - Home (dry)
2RB16xx							0-Alloy Plated	8 - Ends of travel (dry)
MS25Lxx							1-Stainless	9 - Home & End of travel
MS33Lxx							Steel	
MS46Bxx								
MS46Lxx								
Belt								
2HE10xx								
2HE20xx								
2RE12xx								
2RE16xx								
MS46Exx								

* xx Refer to Idenifier table on next page. Indicates Screw Diameter and Lead or Belt unit Gear ratio.

**Y-dimension defines the distance from the motor end plate, to the first set of mounting holes. This dimension can be changed to fit your mounting requirements.

2DB, 2EB, 2HB, 2HE, 2RB, 2RE, MS25, MS33, MS46 Family Identifier

	Ball and Lead	Screw Mod	dels	B	elt Driven Models
	A375in x .100in (preloaded)	2RB12	G - 16mm x 5mm (preloaded)		A - 1:1 Gear Ratio
	B375in x .250in (preloaded)		H - 16mm x 10mm (preloaded)	2RE12	B - 3:1 Gear Ratio
2DB08	C375in x .500in (preloaded)		I - 20mm x 5mm (preloaded)	2RE16	C - 5:1 Gear Ratio
	D375in x .750in (preloaded)	2RB16	J - 20mm x 10mm (preloaded)		D - 10:1 Gear Ratio
	E375in x 1.000in (preloaded)		K - 20mm x 15mm (preloaded)		A - 1:1 Gear Ratio
	B - 12mm x 5mm (non-preloaded)		A25in x .025in (preloaded)	2HE10	B - 3:1 Gear Ratio
2DB12	F500in x .200in (non-preloaded)		B25in x .050in (preloaded)	211210	C - 5:1 Gear Ratio
ZUDIZ	Q500in . 500in (preloaded)		C25in x .062in (preloaded)		D - 10:1 Gear Ratio
	V500in x .200in (preloaded)		D25in x .200in (preloaded)		E - 1:1 Gear Ratio
	D - 20mm x 5mm (non-preloaded)	MS25L	E25in x .250in (preloaded)	2HE20	F - 3:1 Gear Ratio
	G750in x .200in (non-preloaded)	IVISZ5L	F25in x .500in (preloaded)	211220	G - 5:1 Gear Ratio
2DB16	L631in x 1.0in (preloaded)		G25in x 1.000in (preloaded)		H - 10:1 Gear Ratio
	R75in x .500in (preloaded)		H25in x 1.5mm (preloaded)	MS46E	A – 1:1 reduction
	W750in x .200in (preloaded)		I25in x 2.0mm (preloaded)		B - 3:1 reduction
	B - 12mm x 5mm (non-preloaded)		J25in x 3.0mm (preloaded)	101340L	H - 10:1 Gear Ratio A – 1:1 reduction
2EB08	F500in x .200in (non-preloaded)		A375in x .0625in (preloaded)		D - 10:1 reduction
ZLD00	Q500in . 500in (preloaded)		B375in x .100in (preloaded)		
	V500in x .200in (preloaded)		C375in x .125in (preloaded)		
	D - 20mm x 5mm (non-preloaded)		D375in x .200in (preloaded)		
	G750in x .200in (non-preloaded)	MS33L	E375in x .250in (preloaded)		
2EB12	L631in x 1.0in (preloaded)	MODUL	F375in x .375in (preloaded)		
	U - 20mm x 20mm (preloaded)		G375in x .500in (preloaded)		
	W750in x .200in (preloaded)		H375in x 1.000in (preloaded)		
2EB16	H - 1.00in x .250in (preloaded)		I375in x 1.200in (preloaded)		
ZEDTO	T - 1.00in x 1.00in (preloaded)		J375in x 2mm (preloaded)		
	I - 1.50in x .250in (preloaded)		P - 12mm x 5mm (preloaded)		
2EB24	J - 1.50in x 1.00in (preloaded)	MS46B	B - 12mm x 5mm (non-preloaded)		
	Z – 1.50in x 1.875in (preloaded)	1010-00	Q - 12mm x 10mm (preloaded)		
2HB10	G - 16mm x 5mm (preloaded)		R - 12mm x 10mm (non-preloaded)		
211010	H - 16mm x 10mm (preloaded)		K - 12mm x 3mm (pre-loaded)		
	L - 25mm x 5mm (preloaded)	MS46L	L - 12mm x 10mm (pre-loaded)		
2HB20	M - 25mm x 10mm (preloaded)		M - 12mm x 25mm (pre-loaded)		
	N - 25mm x 15mm (preloaded)				

							Linea	•								
	Ball Guide			Bearings			Hard	dware	Cover				Lubrication			
	01	02	O3	O4	O5	O6	07	08	O9	O10	011	012	013	014	015	O16
	Standard Steel	Stainless Steel	Armoloy Plated	Chrome Plate	Raydent Surface	Standard	CR	Polymer	Standard	Stainless Steel	No Cover	Bellows	Shroud	Enclosed	Standard	Clean Room
2DB	Х	Х	Х	Х		Х	Х		Х	Х	Х	Х			Х	Х
2EB	х	х	Х	х		х	х		Х	Х	Х	Х			Х	Х
MS25	Х	Х	Х	Х		Х			Х	Х	Х	Х			Х	Х
MS33	Х	Х	Х	Х		Х			Х	Х	Х	Х			Х	Х
MS46B	Х	Х	Х	Х		Х			Х	Х	Х		Х		Х	Х
MS46E	Х	Х	Х	Х		Х			Х	Х	Х		Х		Х	Х
2RB	Х	Х	Х	Х		Х	Х		Х	х	х	х			х	Х
2RE	Х	Х	Х	Х		Х	Х		Х	Х	Х	Х			Х	Х
2HB	Х		Х			Х			Х	Х	Х	Х	Х		Х	Х
2HE	Х		Х			Х			Х	Х	Х	Х	Х		Х	Х
TF	Х					Х			Х	х				х	х	
TG									Х	Х				Х	Х	
MF	Х					Х			Х	х				х	х	
MG									Х	Х				Х	Х	
DS4/6	Х	Х				Х				Х				Х	Х	
URS	Х					Х			Х		Х		Х		Х	Х

7.3 Appendix C: Environmental Conditions Custom Options